

Backdoors for Constraint Satisfaction

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Gregory Gutin's 60th Birthday Conference
January 7th & 8th 2017





...every stone
a theorem

Gregory and Constraint Satisfaction

Gregory has published several papers on constraint satisfaction problems (Max-r-CSP, Max-Permutation-CSP, Workflow-CSP)

Backdoors for Constraint Satisfaction

Joint work with

Robert Ganian, Serge Gaspers, Neeldhara Misra,
Sebastian Ordyniak, M.S. Ramanujan, and Standa Živný

Different Problems \subseteq CSP

- Graph k-Coloring, k-SAT, k-Clique, Graph Homomorphism, Conjunctive Database Query,
- All these problems (and many more) can be seen as special cases of a very general problem, the **Constraint Satisfaction Problem**
- Introduced by Montanari 1974, has been focus of intensive research (TCS, AI, Combinatorics, Algebra,...)

The Constraint Satisfaction Problem (CSP)

- Instance: $I=(V,D,C)$ where
- V is a finite set of variables
- domain D is a finite set of values
- C is a finite set **constraints**
- $f:V \rightarrow D$ satisfies $C=((x_1,\dots,x_r),R^r)$
if $(f(x_1),\dots,f(x_r)) \in R^r$

A constraint for
3-coloring

u	v
Red	Blue
Red	Green
Blue	Red
Blue	Green
Green	Red
Green	Blue

instantiating variables

u	v	w
1	1	1
1	0	1
0	1	1
0	0	1

set u=1

instantiating variables

u	v	w
1	1	1
1	0	1
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u v w			v w	
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0	0	1		

set $u=1$

Generalizes to: partial assignment **f**
applied to CSP instance **I** yields a
new CSP instance **I[f]**

Complexity of CSP

- CSP is NP-complete (even restricted to Boolean domain or binary constraints)
- Tractable subproblems (**islands of tractability**)
 - **language restrictions:** how do the constraint relations look like, no matter how the variables and constraints interact
 - **structural restrictions:** how do variables and constraints interact, no matter how the constraint relations look like

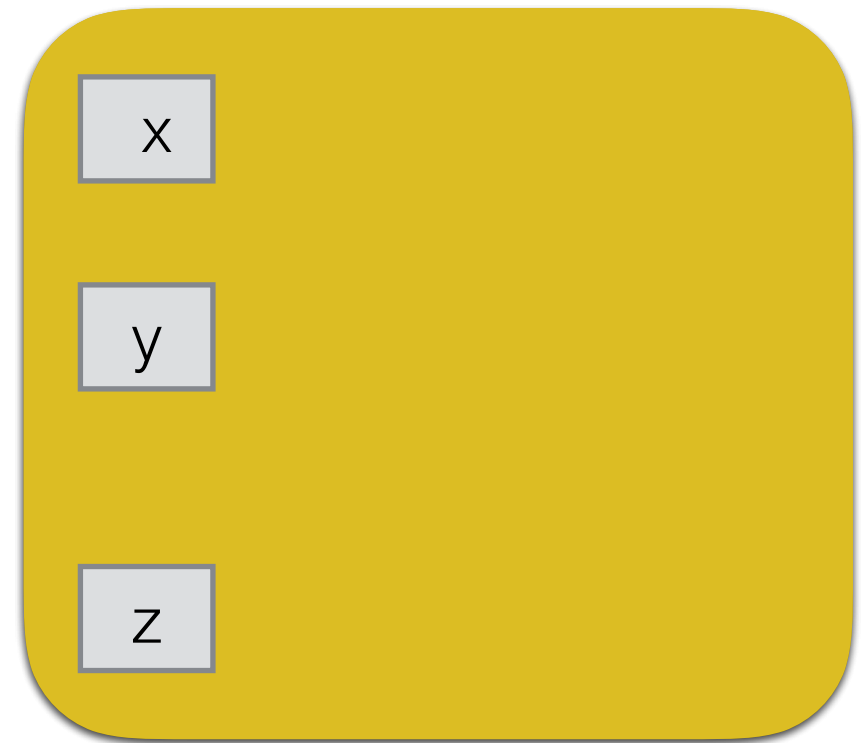
Language Restrictions

- **CSP(Γ)** consists of all CSP instances whose constraints use relations from the set Γ (called the **constraint language**)
- **Schaefer's Dichotomy Theorem (1978)** (*1800 citations*)
For every *Boolean* Γ , CSP(Γ) is either tractable or NPc.
- **Feder-Vardi-Conjecture (1993)** (*2000 citations*)
For every Γ , CSP(Γ) is either tractable or NPc (there circulate rumours that the conjecture has been established)

How to deal with instances that are close to an island of tractability?

Backdoors

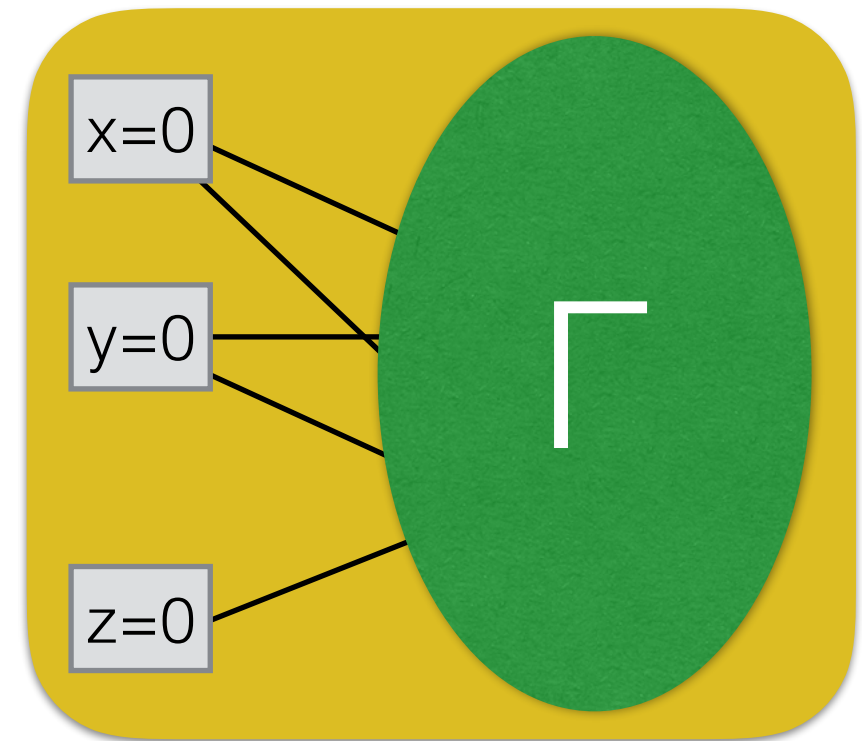
Instance belongs to $\text{CSP}(\Gamma)$ for
all possible instantiations of
backdoor variables



- A strong **backdoor** of a CSP instance into an island of tractability **C** is a set B of variables such that **for each possible instantiation** of the variables in B , the reduced instance belongs to **C**
- Call **C** the **base class** of the backdoor
- Backdoors were introduced by [Williams, Gomes, Selman 2003]
- Distance to island: **size of smallest backdoor**

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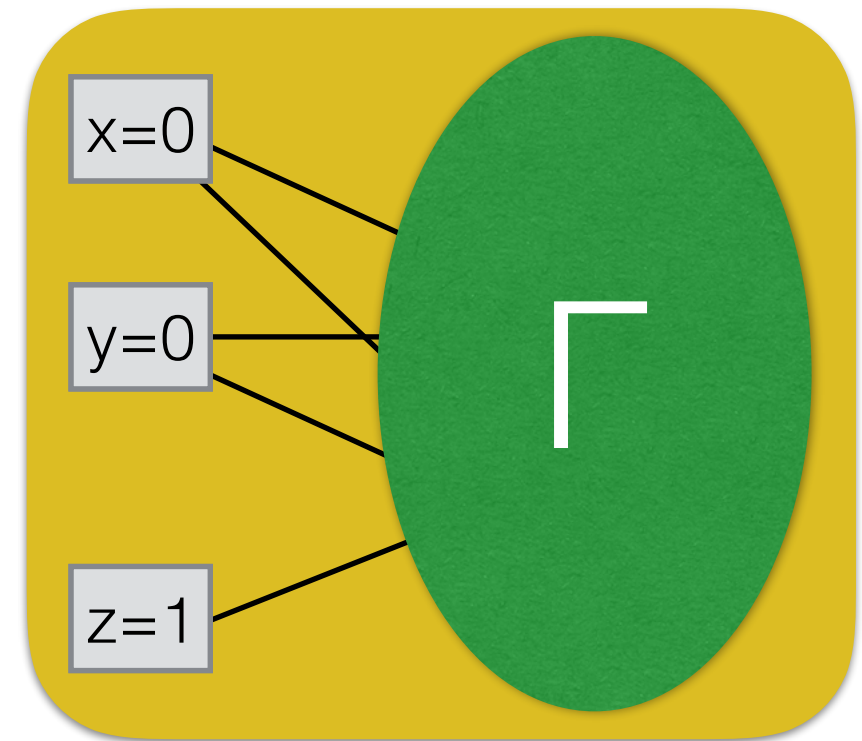
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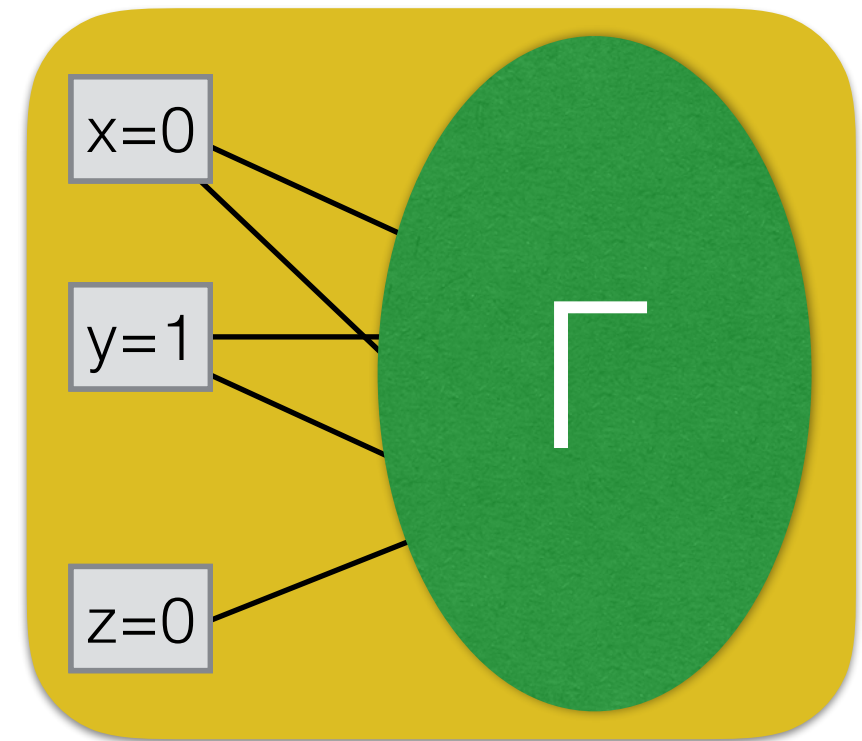
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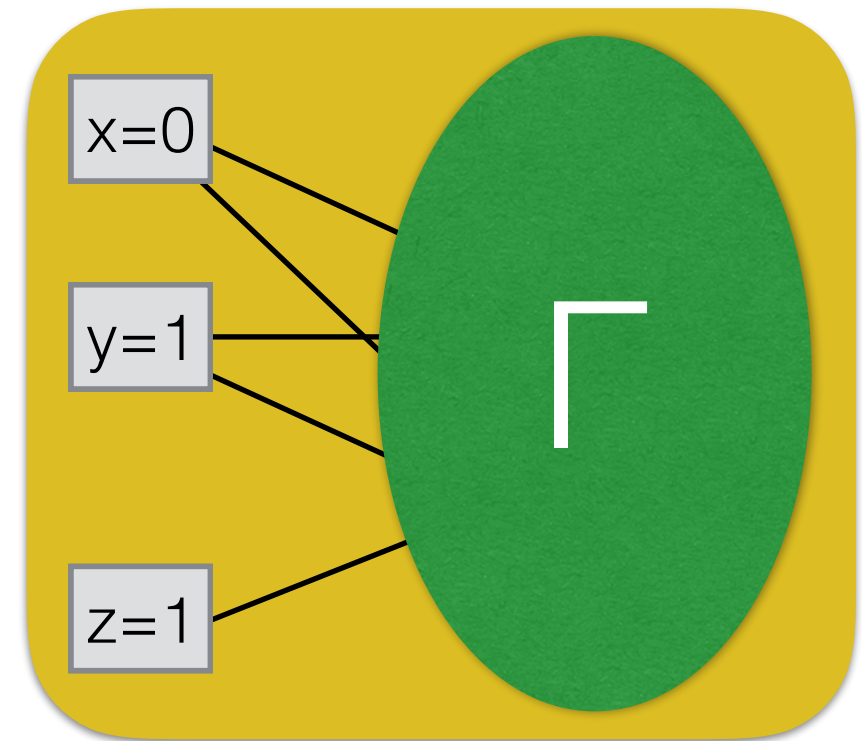
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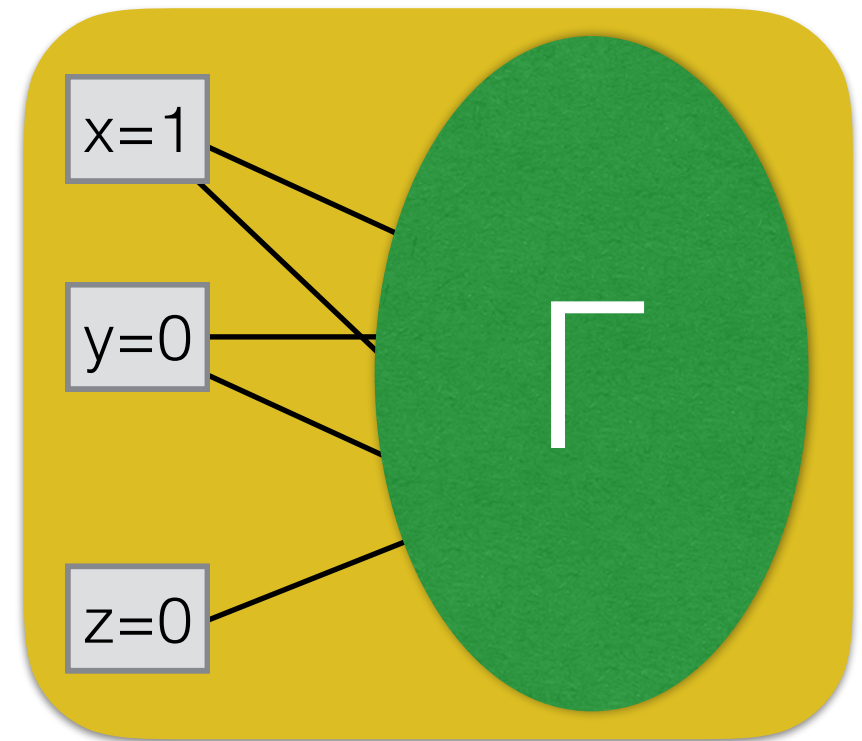
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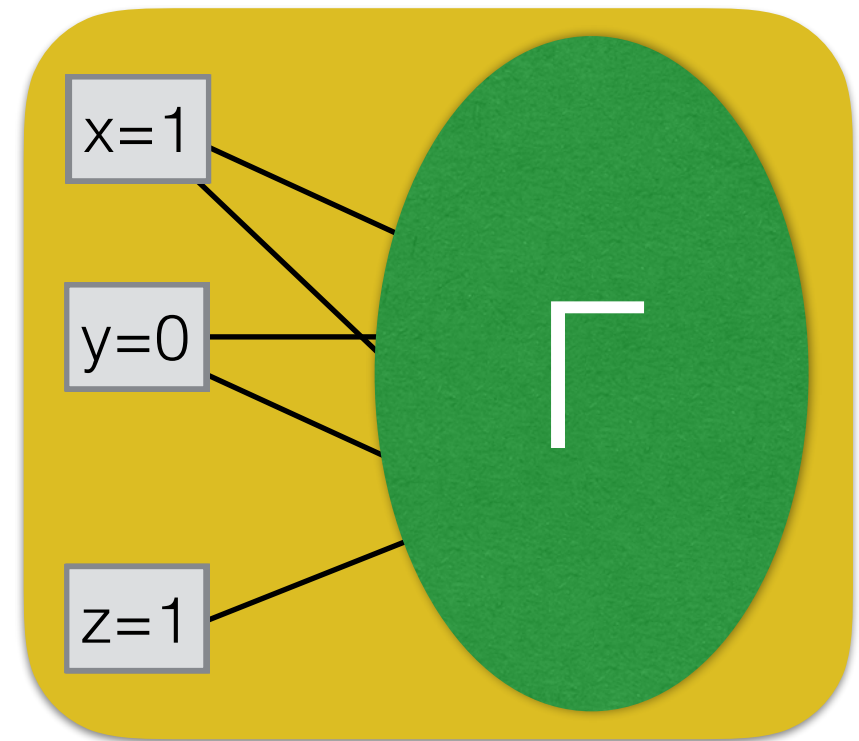
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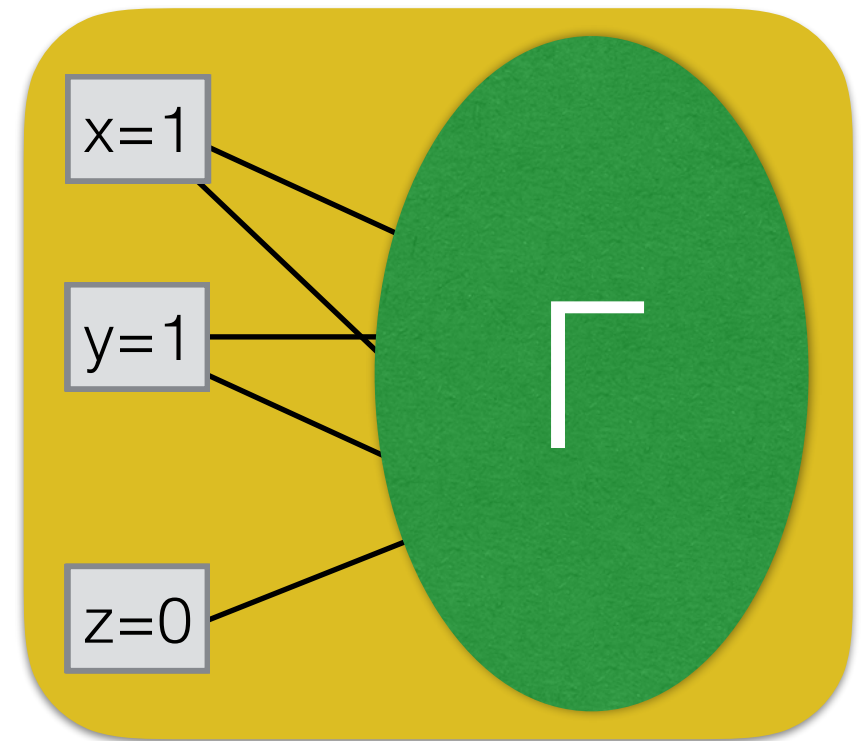
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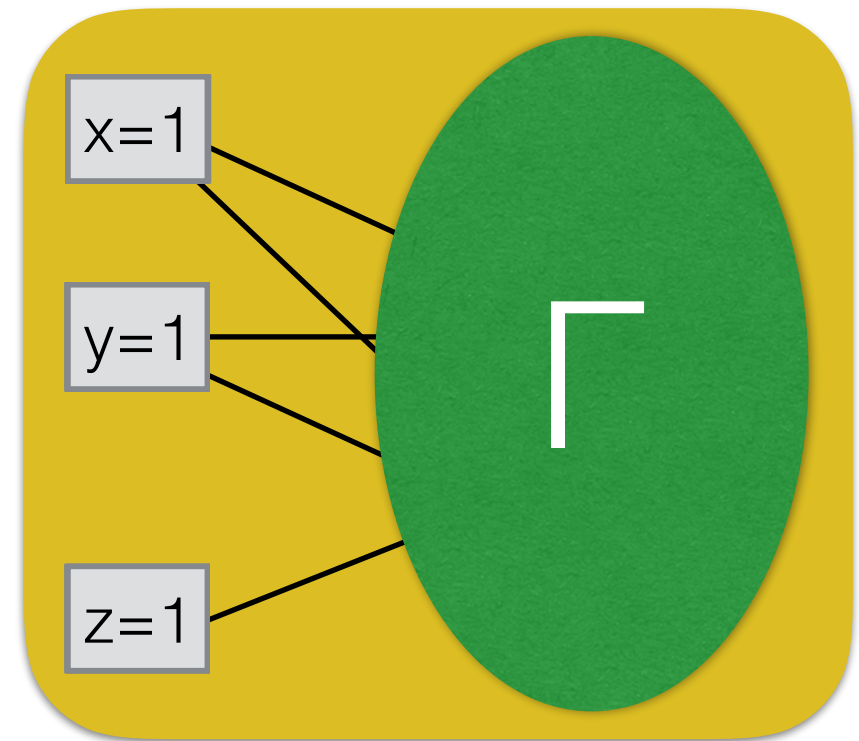
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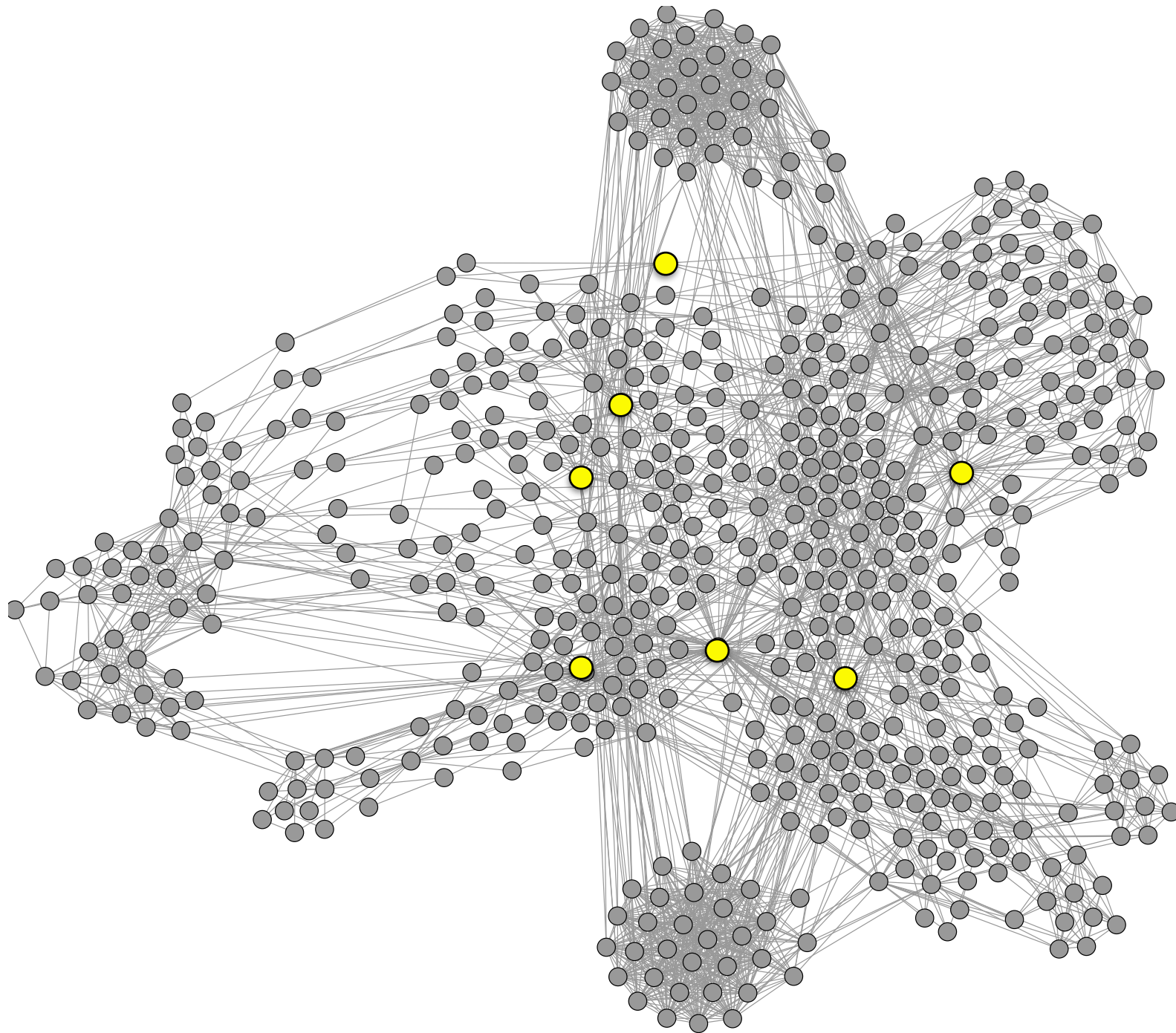
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when FPT?

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FPT if D is constant

backdoor can be a needle
in the haystack!



Basic Result

- If **domain size** is unbounded, then backdoor evaluation is not FPT
- If **arity** is unbounded, then backdoor detection is not FPT (unless $FPT=W[2]$) by standard reduction from HS
- Thus, for $CSP(\Gamma)$ we must restrict ourselves to **finite** constraint languages Γ
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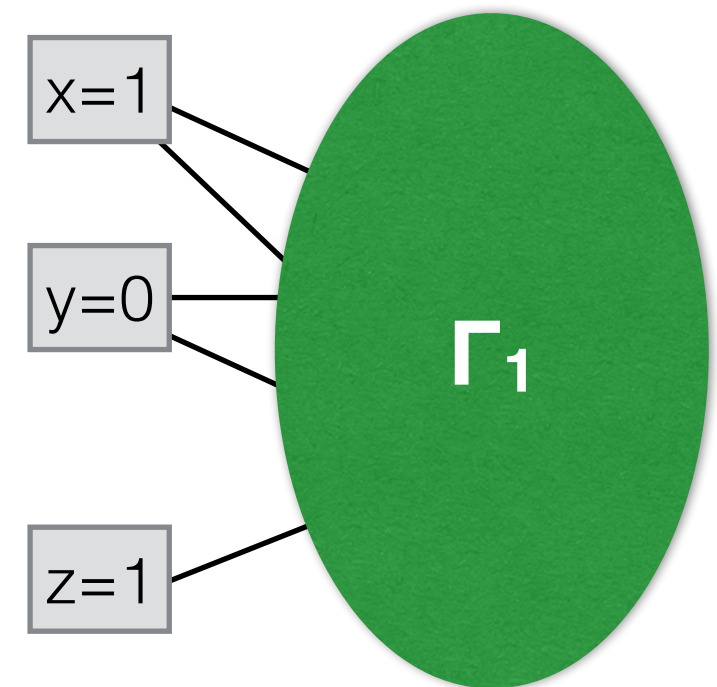
bounded search tree

Extensions: **Heterogeneous** base classes

Each assignment to backdoor
can put the formula on a
different island

Can yield arbitrarily smaller
backdoors

notation: **CSP**(Γ_1) $\cup \dots \cup$ **CSP**(Γ_r)

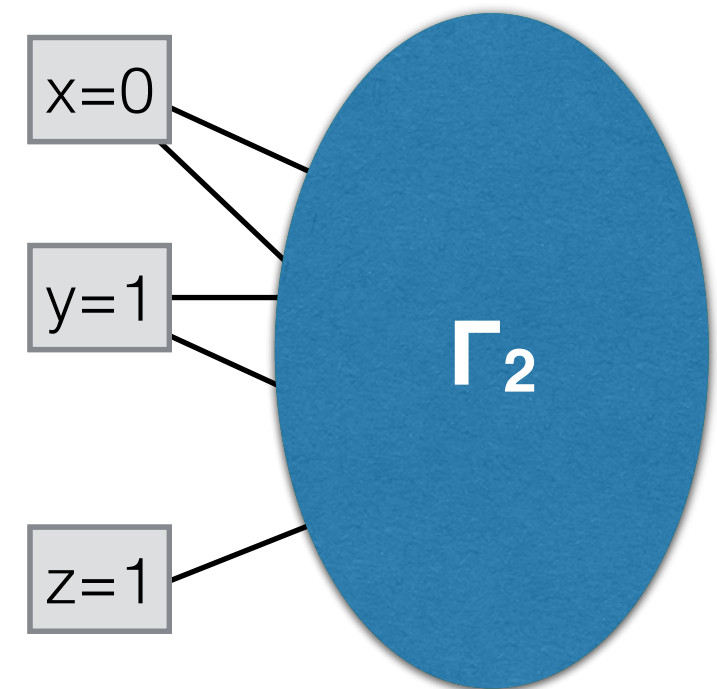


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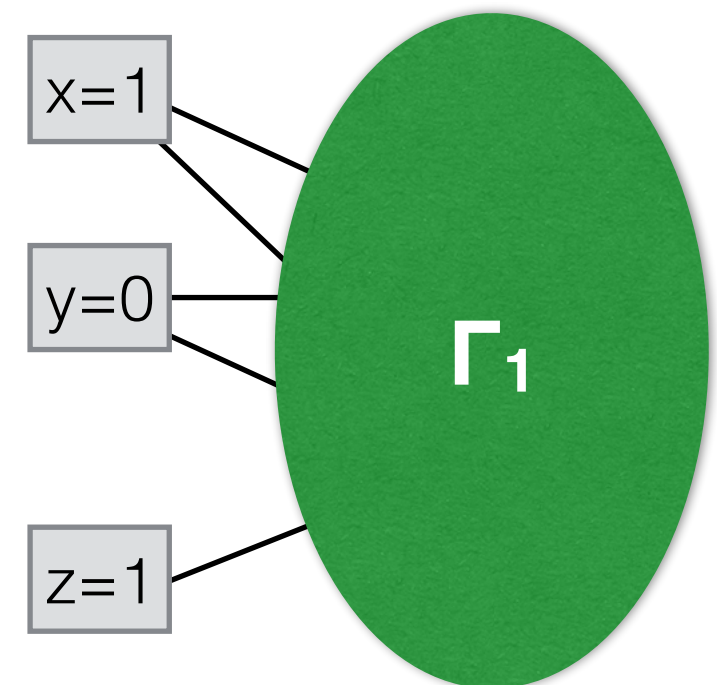


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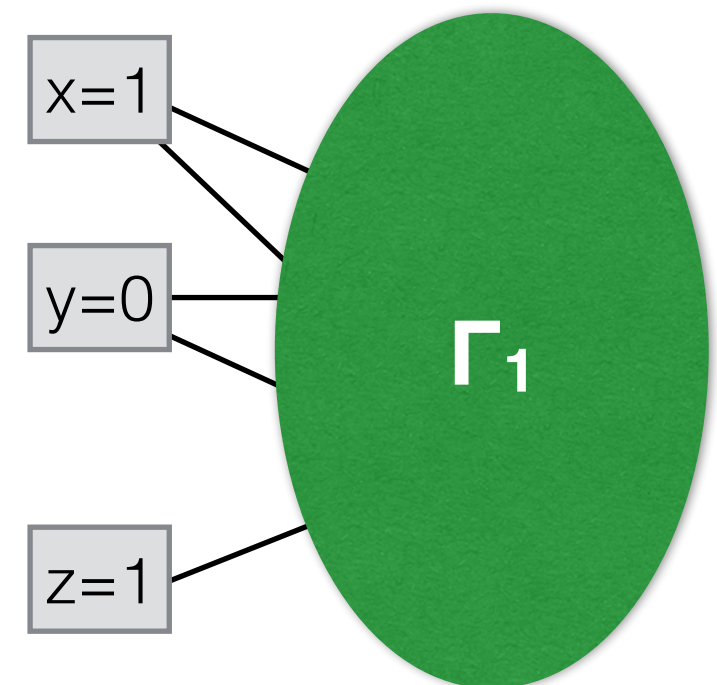


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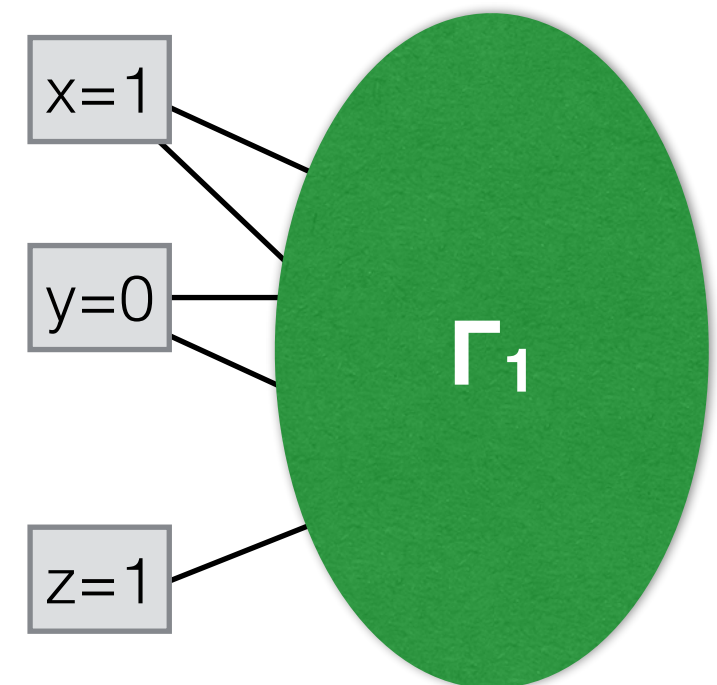
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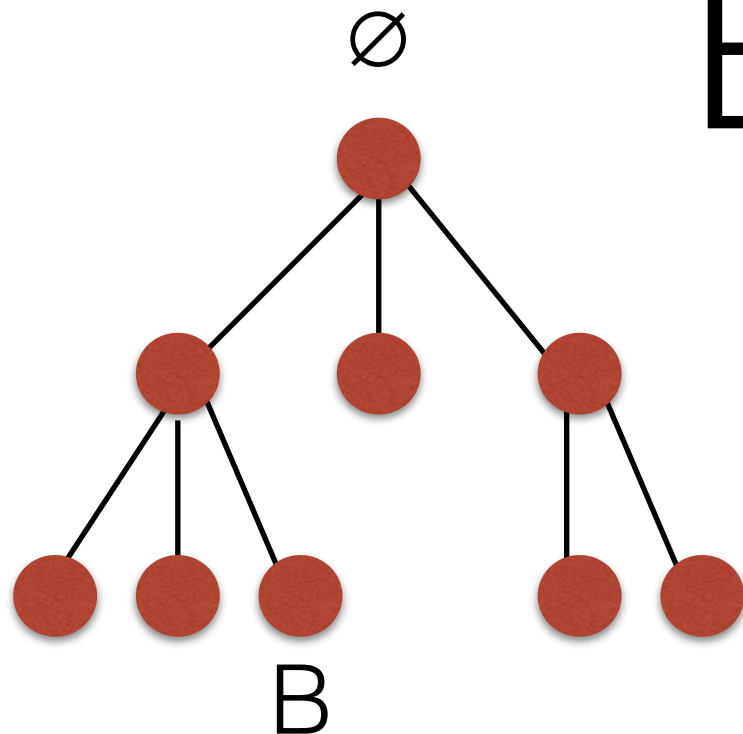
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Branching



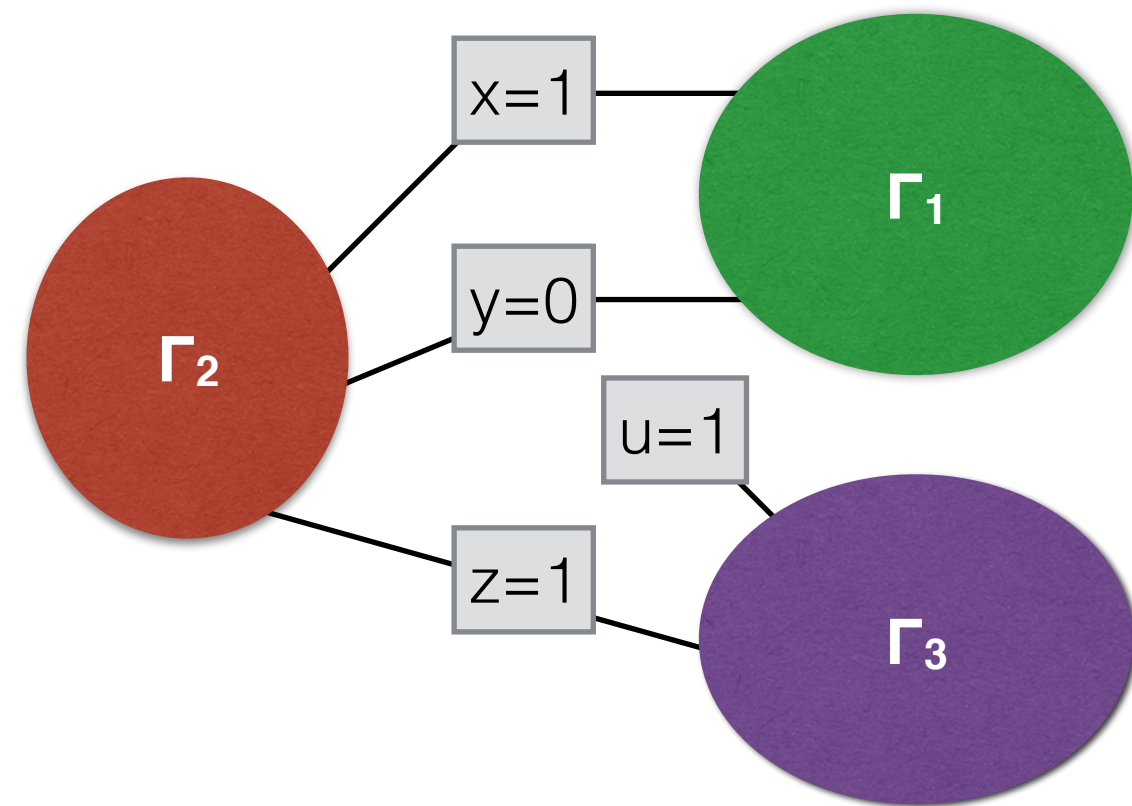
- If B is not a strong backdoor, then there is some $\mathbf{f}: B \rightarrow D$ such that $\mathbf{I}[\mathbf{f}] \notin \text{CSP}(\Gamma_1) \cup \dots \cup \text{CSP}(\Gamma_r)$.
- In particular, for each i there exists some $c_i \in \mathbf{I}[\mathbf{f}]$ such that $c_i \notin \Gamma_i$.
- Now branch into $B \cup \{v\}$ for each variable v that appears in c_i for some i .

Extensions: **Scattered** base classes

Each connected component of
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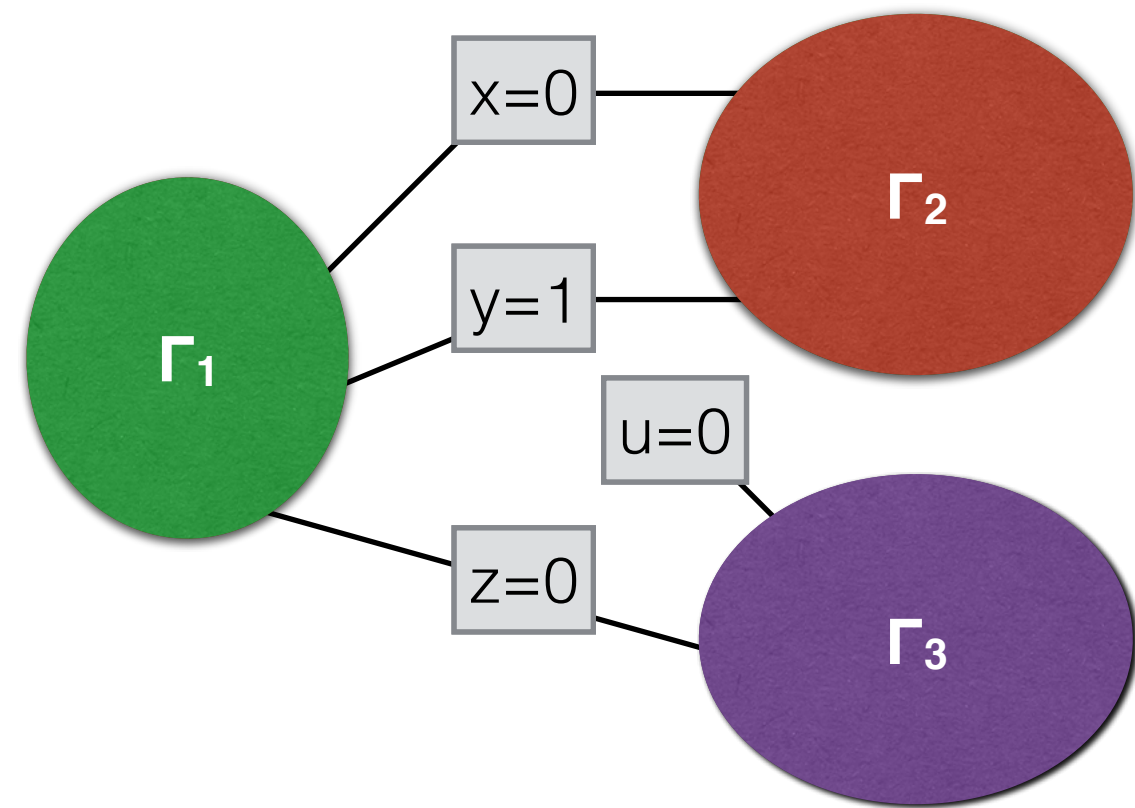


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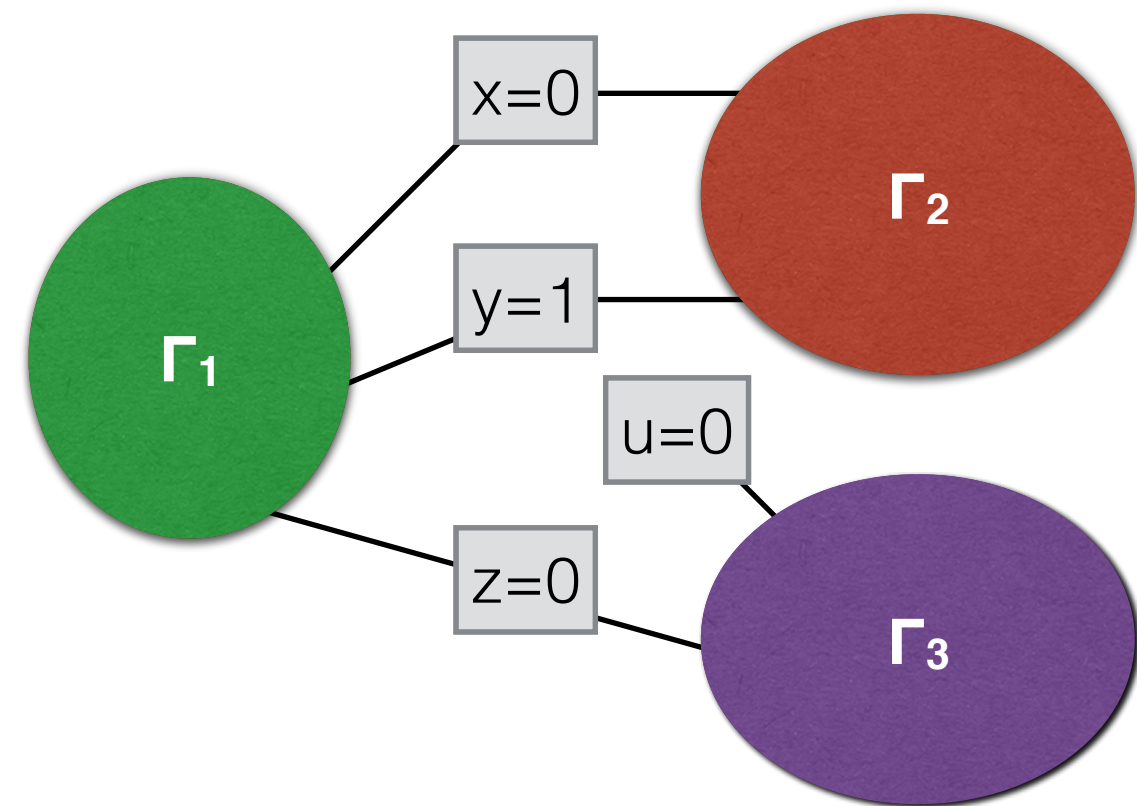


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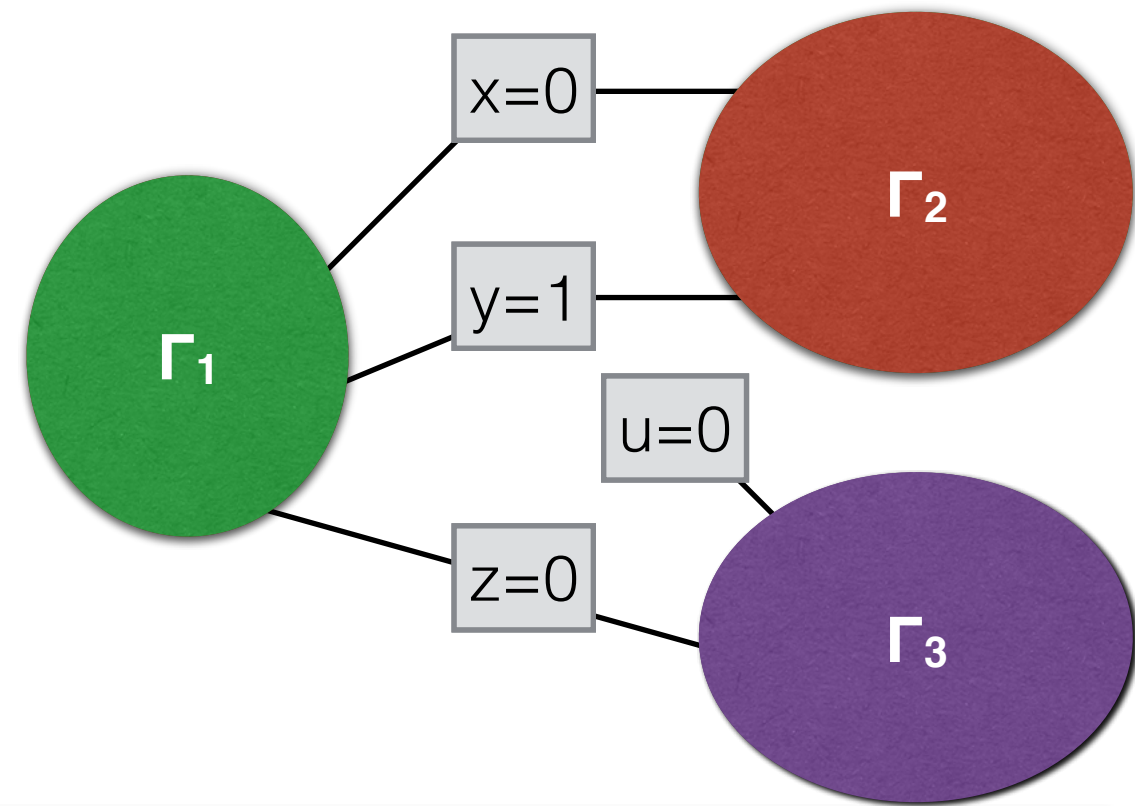
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Iterative compression, tight separator sequences, etc.

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- Actually: FPT by treewidth if domain is bounded

Incomparable parameters

size of
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 $\text{CSP}(\Gamma)$

treewidth of
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graph

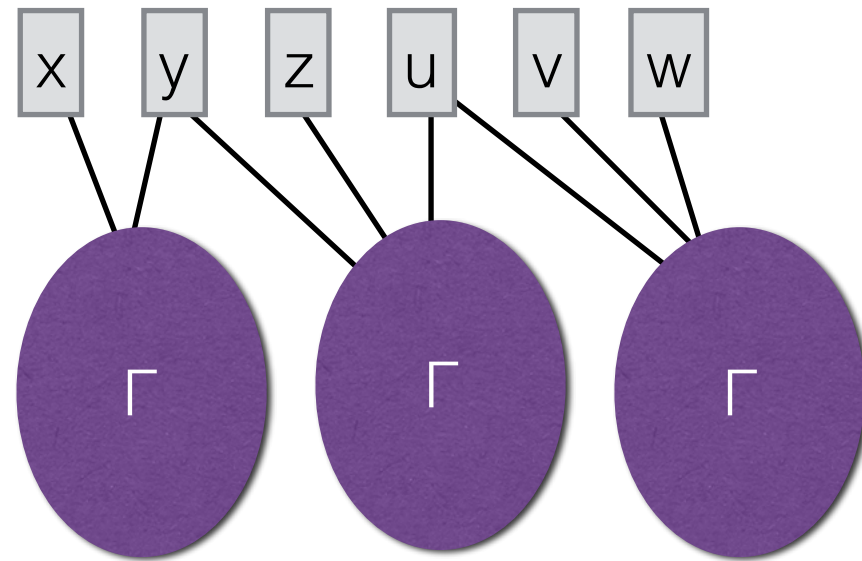
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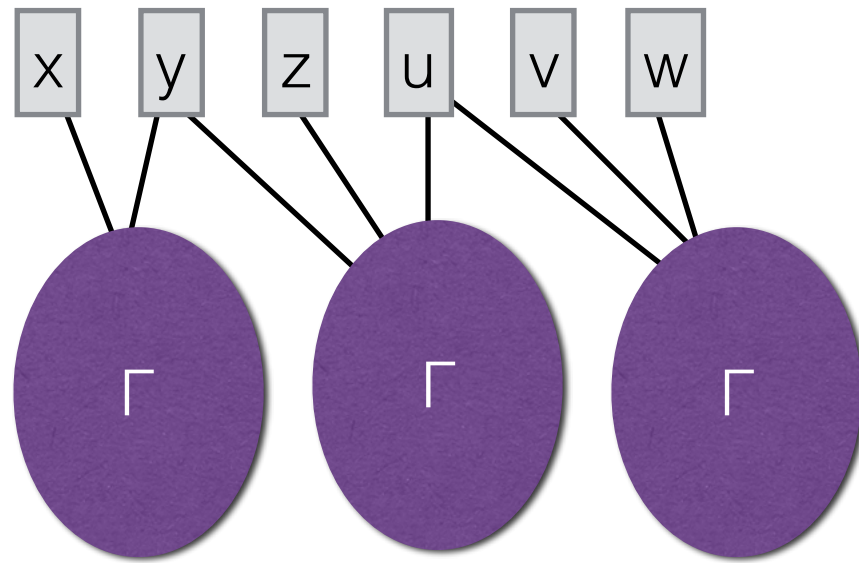
treewidth of
constraint
graph

backdoor treewidth wrt Γ

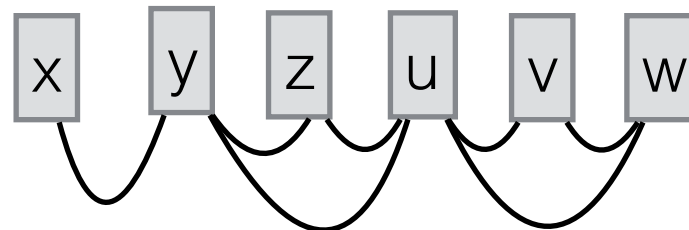
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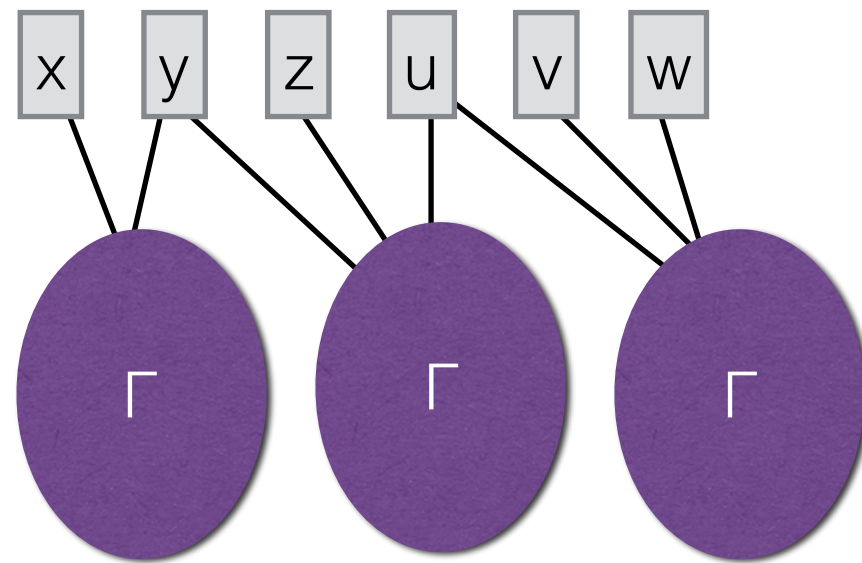
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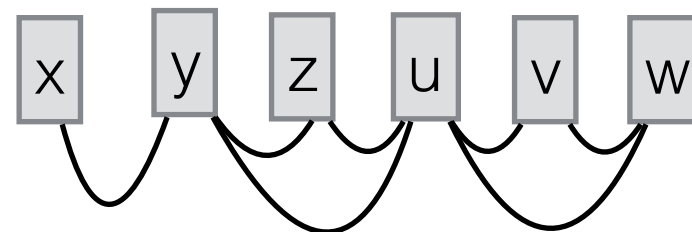
torso graph:



backdoor treewidth

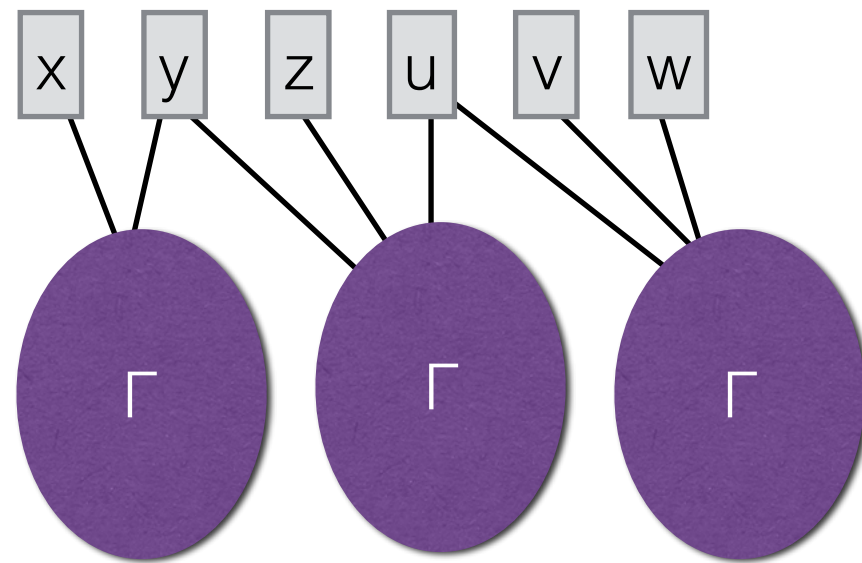


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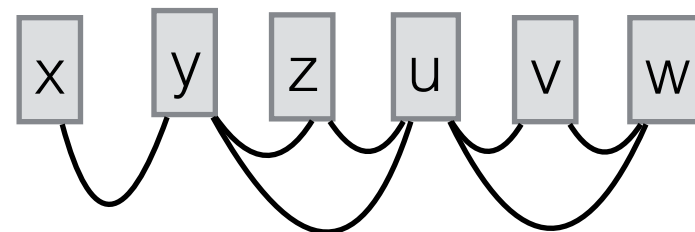


the **backdoor treewidth** wrt Γ is the minimum treewidth over the torso graphs of all strong backdoor sets into $\text{CSP}(\Gamma)$

backdoor treewidth



torso graph:



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$\text{backdoor treewidth} \leq \min\{ \text{treewidth}, \text{backdoor size into } \text{CSP}(\Gamma) \}$

Results

THM: CSP is FPT parameterised by the backdoor treewidth wrt Γ for any finite, recognisable, and tractable Γ .

- Finding the backdoor that minimises the backdoor treewidth is FPT.

Algorithm based on ideas related to “boundaried graphs”, “replacement framework”, and “recursive-understanding technique”. Ultimately it relies on a lemma stating a finite state property.

- Once the backdoor is found, the instance can be compiled into a CSP of bounded treewidth, and then solved using Freuder’s algorithm in time D^k

Future work

- Extend result on scattered base classes to infinite sequences of constraint languages $\Gamma_1, \Gamma_2, \Gamma_3, \Gamma_4, \dots$
- Extend backdoor treewidth to other graph invariants of torso graph wrt specific constraint languages
- Avoid detection and solve directly



Grisha, happy
B-day!